ENGINEERING TOMORROW



Data Sheet

Superheat controller and stepper valve driver Type **EKE 1A,B,C (PV05), 1D (PV02)**

For air conditioning, commerical/Industrial heatpumps and refrigeration applications



The flexible pre-programmed EKE superheat controller from Danfoss provides ultimate software control, allowing you to tailor the performance of your system to your exact requirements. EKE is ideal for controlling a wide range of commercial air conditioning and refrigeration applications, such control helps you to achieve the highest efficiency in the system reducing the operational cost by up to 20% with minimal effort. EKE is generally used where there is a requirement for accurate control of superheat or temperature control in connection with air conditioning and refrigeration. The superheat is regulated to the lowest possible value within a short period of time. It regulates the superheat of the evaporator by charging optimally even when there are great variations of load resulting in reduction of energy consumption and operational cost

Typical Applications

- Chillers
- Processing plant / Cabinet cooling
- Cold store (air coolers)
- A/C plant / Air conditioning
- Commercial and Industrial heat pumps
- Transport cooling
- Stepper Motor Driver

Danfoss

Portfolio overview

Table 1: Portfolio overview

| Features | | EKE 1A | EKE 1B | EKE 1C | EKE 1D |
|------------------------------------|--|--|--------|-----------|-----------|
| | | | | | |
| Power supply: | 241/46/06 + 200/ | | | | |
| Power Supply Type | 24 V AC / DC ± 20% | • | • | • | • |
| Battery Backup input | 18-24 V DC | • | • | • | • |
| Class of insulation | | | Cia | ss II | |
| Data communication | | | | | |
| MODBus | RS 485 RTU | | • | • | <i>a</i> |
| Wired CANbus | | | | (4 wires) | (3 wires) |
| CANbus RJ 12 | Danfoss MMI service port | • | • | • | • |
| Inputs:: | | | | | |
| Number of temperature sensors | | 1 | 2 | 3 | 2 |
| Temperature sensor types | PT1000 | | | • | |
| | NTC 10K, type EKS | • | • | • | • |
| | NTC 10K, type ACCPBT | • | • | • | • |
| | NTC 10K, type Sensata | • | • | • | • |
| Number of Pressure sen- sor | | 1 | 1 | 2* | 1 |
| Pressure Transmitter | Ratiometric 0.5 - 4.5 V | • | • | • | • |
| types | Voltage signal 0 – 10 V | | • | • | • |
| | Current signal 0 – 20 mA | | | | |
| Share Pressure Signal | Hardware (Up to 5 devi- ces) | • | | | |
| | Via wired CANbus (not possible to share ratio- metric sensor) | | | | |
| | Via MODbus | | • | • | |
| Number of external refer- ences | | 1 | 1 | 1 | 1 |
| External reference | 0-20mA | | | • | |
| | User defined current | | | • | |
| | 0-10V | | • | • | • |
| | 0- 5V | | • | | • |
| | User defined voltage(max 10V) | | | | |
| Digital input Dry contact | | 3 | | 2 | |
| Outputs | | | | | |
| Digital output | | | | 1 | |
| Relay | Normally Open | 3A General purpose, 250V ac, 100k 2A General purpose, 250V ac, 100k | | | |
| | Normally closed | | | | |
| Relay Function | | Alarm relay or LLSV (Liquid Line Solenoid Valve) | | | |
| User interfaces | Koolprog Software tool | • | • | | |
| | MMIGRS2 screen | • | | • | |
| | Master controller | | • | | |
| | | | | | |

*The 2nd pressure sensor is mounted on Al4



Functions

The EKE 1x products supports a wide range of functionalities illustrated in table 3 and 4. Check the user guide for more detail about configurations and other detailed options.

| Hardware functions | | |
|--------------------------------------|--|---|
| Digital inputs | Used to interact with the EKE for systems where the EKE is not connected to a system controller via data communication. The available digital inputs DI can be used for the following functions: a. Injection control ON/OFF(DI1). b. Defrost sequence (DI2). c. Heating and cooling selection mode (DI2) d. Preset OF (DI2) | |
| Digital Output (Relay) | | will operate when refrigeration is required situations and when the controller is de-energized. gured for solenoid valve, max capacity or for alarm function. NO NC NC NC NC NO NO |
| Handling power failure | For safety reasons the liquid flow to the evaporator must be cut off in case of power failure. The valve's stepper Motor will remain open in power failure situation There are two ways of coping with this situation One of the following two solutions can be applied in the system • Mounting of a solenoid valve in front of EEV (using LLSV relay signal from EKE) • Mounting of a battery backup for EEV valve (Use Danfoss EKE 2U) | |
| Analog Inputs | External Reference Signal: Used for: Driving the stepper motor valve to a desired opening degree (Driver Mode) Displacing temperature reference, superheat reference or max OD The voltage signal e.g., 0 – 10 V can be used in all EKE controllers whereas current signal e.g 0 – 20 mA signal is only available in EKE 1C | |
| Communication: RS485 Modbus / CANbus | The controller can be provided with data communication for connecting to other devices in the systems. In this case, monitoring and data collection can be performed from one device i.e., PLC – which will be beneficial for the diagnostic or during the installation processes. For example, it is possible to substitute the physical sensors of the EKE controller by writing sensor values via Bus. The frequency of update should be according to the Modbus maximum update interval G004 (Refer to parameter list) | |
| Light-emitting diodes (LEDs) | frequency of update should be according to the Modbus maximum update interval G004 (Refer to parameter list) Two sets of light-emitting diodes make it possible to follow the operation status of the valve and the controller. The indicate the following • Power/data transmission and Alarm/Error indication • Stepper valve operational status LED status: Red constant valve is closed Green constant valve is fully open Flashing red valve is moving in close direction Flashing red valve is moving in open direction Flashing red and green Error | |



Table 3: Control Functions

| Valve Driver | The EKE controls the opening degree of the valve, the control signal can be an analog signal or a value via communica- tion bus |
|---------------------------------|--|
| | • Fixed Superheat The controller keep the superheat at a fixed reference value determined by the user. SH fixed setpoint can be varied according to the need of application. |
| | • Minimum Stable Superheat (MSS): The superheat control algorithm will attempt to regulate the superheat down to the lowest stable value between the minimum superheat setting, "Min SH" and the maximum superheat setting, "Max. SH". |
| Superheat Reference Calculation | • LoadAP Superheat LoadAP is a kind of preprogrammed MSS curve. In Load ap application, SH reference follows a defined curve as shown in the diagram. This two-point curve is defined by SH max and SH min, this method will give a robust SH reference and can in many cases be the best fit for systems. |
| | • Delta temp. superheat SH reference is calculated as a ratio between the media temperature and evaporator tempera- ture. This reference mode is only possible if media temperature (S3) sensor is available and if the system uses fin and tube evaporator. |
| | EKE has a feature to regulate the temperature control. This can be done with either |
| Temperature Control * | • Thermostat cut in/cut out function: if temperature is above the set point + differential, cooling is started with maximum cooling capacity. In maximum capacity superheat is controlled to be on superheat set point. Cooling is active until the temperature is below set point. |
| | • Modulating Thermostat (MTR): When temperature is getting close to the MTR reference the cooling capacity gradually reduce so that the temperature can be stable on the MTR reference and the superheat will be floating. |
| | • Failsafe operation: During operation if sensors error occurs, the valve position can be set to full close, fixed |
| | opening degree or average calculated OD as required. |
| | • Superheat close: When the superheat is below a set minimum value, the valve will close faster to protect the compressor from the risk of getting liquid in the suction line and bring the superheat back to superheat reference. |
| Protection Functions | • Maximum Operating Pressure (MOP): To reduce the strain on the compressor, a maximum operating pressure is set. If the pressure comes above this limit the controller will control the valve to provide a lower pressure instead of a low superheat. |
| | • Low Operating Pressure (LOP): known as Cold start feature, it allows applications such as heat pumps to operate at lower ambient conditions to prevent compressor from stopping due to low suction pressure in the startup phase. |
| | • High Condensing temperature protection (HCTP)**: High condensing temperature protection will make sure that the load on the condenser is reduced in case a too high condensing temperature is reached. This is done by limiting the valve opening degree. |
| | • Minimum S4/leaving media (freeze protection) *: Lowers the flow in the expansion valve if temperature of leaving media out of the evaporator is below a minimum value set by the user. |
| | • Fast Start up: Quickly open an EEV valve when compressor turns ON to prevent too low suction pressure as well as for faster stabilization of superheat or temperature set point. This can be ensured by setting either P-control, Start opening degree with protection or Fixed opening degree without protection. This start up condition is kept until the start time expire or superheat reaches at setpoint. |
| Other Functions | • Defrost sequence: The controller does not itself handle defrost of the evaporator. It is however possible to enter a special defrost sequence which will overrule the normal control of the valve. |
| | • Manual control: The valve can be controlled manually by setting the desired opening degree via Analog signal or com- munication bus used for commissioning purpose. A special service mode is also available for service and testing purpose. |
| | • Service mode: Service mode is designed to provide a very simple way of operating the valve for diagnostic and service purpose. There is neither application nor protection in this mode. The user can open and close the valve using simple button presses on MMIGRS2. |
| | |

*Not available in EKE 1A

**Only Available EKE 1C



Applications

EKE series devices are used where precise control of superheat in air conditioning system is needed. It helps achieving high energy efficiency and reliable operation

EKE serves 2 main applications:

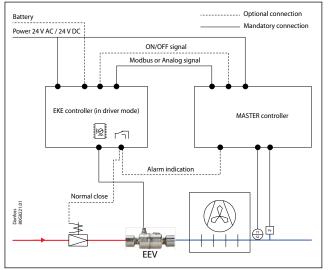
- Driver Mode
- Controller Mode
 - 1. Superheat controller
 - 2. Temperature controller

Driver mode

Driver Mode: A master is commanding the valve open degree to the EKE controller. The control signal can be fed for example by:

- Analog signal e.g., 0 10 V, a 4 20 mA
- Bus communication via RS485 (Modbus RTU).

Figure 1: EKE as Driver Mode



O NOTE:

'Normal closed' valve in front of EEV is optional alternative to a battery backup solution which closes the EEV in case of power fail. The Digital output can also be used as alarm indication to the master controller. The Master can send a start signal to EKE DI terminals

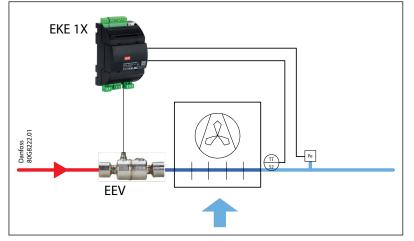
Controller Mode

Controller Mode:

Superheat Control: EKE can serve as a PI controller that controls the superheat of the evaporator based on a pressure Pe and temperature (S2) sensors. In superheat mode the controller will control the superheat to be stable and close to the superheat reference. If superheat is too low the flow in the expansion is decreased and superheat will be higher



Figure 2: Superheat control application



Temperature controller The temperature control is an ON/OFF thermostat that opens/closes the stepper valve or modulating thermostat that regulates temperature more smoothly following a temperature reference point. The temperature control can be accomplished via a signal from temperature sensor S3 placed in the air flow before the evaporator or S4 placed in the air flow after the evaporator.

EKE has 2 methods of controlling temperature:

- ON/OFF thermostat
- Modulating thermostat (MTR)

The need for cooling can either be defined by the incoming media (S3) or the outgoing media (S4) temperature

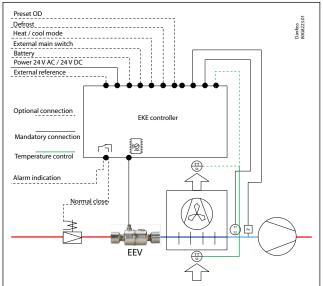


Figure 3: Temperature control application

O NOTE:

EKE1A can only work in the driver mode or superheat control mode as it supports only one temperature sensor input



Product specification

Technical data

Table 4: General specification

| Feature | Description |
|-------------------|---|
| Power supply | Galvanic isolation by switch mode power supply Input voltage rating (AC): 24 V AC \pm 20 % (min.19.2 V AC - max. 28.8 V AC Input frequency (AC): 50 / 60 Hz Input voltage rating (DC): 24 V DC (min. 20 - max. 40 V DC) Provides 5 W at 5 V and 15 V outputs isolated from the 24 V input Insulation between power supply and the extra-low voltage. Class of insulation Class II |
| Power Consumption | Total Power consumption with following valve in operation and MMIGRS2 con- nected to the controller: CCMT 16 - CCMT 42: 15VA/10W ETS 8M (Bipolar), CCMT L ETS 6: 11 VA / 7.5W ETS 12C - ETS 100C: 20VA / 14W KVS C: 20VA / 14W ETS 12.5 - ETS 400 7 VA / 5W CCMT 2 - CCMT 8 7 VA / 5W CTR 20: 7 VA / 5W |
| Plastic Housing | DIN rail mounting complying with EN 50022 Self-extinguishing V0 according to IEC 60695-11-10 and glowing / hot wire test at 960 °C according to IEC 60695-2-12 Material used for Enclosure are UL94-V0 and RoHS compliant Ball test: 125 °C according to IEC 60730-1 Leakage current: ≥ 250 V according to IEC 60112 |
| Connectors | Plug able Screw connector Pitch 3.5 mm, relay and power connector Pitch 5 mm, CAN MMI: Modular Jack 6P4C Material used for connectors are RoHS and UL approved |

Table 5: Electrical specification

| Feature | Туре | Description |
|------------|------------------------|--|
| | Short circuit | Motor driver: dissipative over current protection |
| Protection | Over voltage | Analog input: current limit and internal clamp diode Digital input: current limit and internal clamp diode Communication: transceiver IC |
| | Over Temperature | Motor driver: thermal shutdown at 150 °C |
| | Unstable Digital Input | Continuous variation of the digital input state |

Table 6: Input/Output

| I/O | Туре | Specifications |
|---------------|-------------------------|--|
| | | Max. 15 V input voltage Open circuit HW diagnostics available for voltage input on: AI3, AI4 (EKE 1C) AI4 (EKE 1A and EKE 1B). WARNING: Do not connect voltage sources without current limitation (overall 80 mA) to analog inputs while unit is not powered. |
| | 0 – 5 V | EKE 1C (Al3, Al4) and EKE1A/1B/1D Al3 Accuracy \pm 40 mV, resolution 1.2 mV. |
| | 0 – 10 V | EKE 1C (Al3, Al4) and EKE1A/1B/1D Al3 Accuracy \pm 50 mV, resolution 2.5 mV. |
| Analog inputs | 0 – 20 mA (EKE 1C only) | Accuracy \pm 100 $\mu\text{A},$ resolution 10 $\mu\text{A}.$ Input resistance: <100 Ω |
| | NTC Sensor | NTC temperature probes: 10 kΩ at 25 °C range: 300 kΩ to 100 Ω Accuracy: 50 – 120 °C: 1.5 K, -40 – 50 °C: 0.4 K, 0 °C: 0.2 K Resolution: ≤ 0.1 K, ≤ 0.3 K (EKC 1C, Al5) |
| | Pt1000 sensor | Range: 723 Ω to 1684 Ω Accuracy: ≤ 0.5 K Resolution: ≤ 0.1K |
| | Pressure Sensor | Type: Ratiometric Accuracy: 1.6 % Range: 0.5 - 4.5 V Resolution: 1.2 mV Supply voltage: 5 V DC / 15 mA, overload protection approximately 150 mA |



Superheat controller and stepper valve driver, Type EKE 1A, 1B, 1C, 1D

| 1/0 | Туре | Specifications |
|----------------------|--|---|
| Digital Input DI | Voltage free contacts | Steady current of 1 mA (EKE 1C only). A cut-in input will activate a function. Cleaning current of 100 mA at 15 V DC. On: RIL <= 300Ω . Off: RIH >= $3.5k\Omega$. No destructive if Vbat + is connected to DI (only for DI on bottom pcb). Min. pulse time 64 ms. |
| Digital output (D01) | Relay | Normally Open: 3 A General purpose, 250 V AC, 100 k cycle Normally Open: 3 A Inductive (AC-15), 250 V AC, 100 k cycle Normally Closed: 2 A General purpose, 250 V AC, 100 k cycle |
| Stepper motor | Bipolar stepper Motor Output | Other Valves: • speed 10 - 400 pps • drive mode full step, half step, 1/8 microstep • max. peak phase current: 1.2 A (848 mA RMS) • max. output power 12 W |
| Battery backup | | VBATT: 18 – 24 V DC: Leakage: <15 μA @30 V DC Optional: critical low alarm below 12V Optional: low alarm at 17 V, high voltage alarm at 27 V The valve will not close at power fail if voltage is higher than 27 V Required power to do 1 closing of stepper valve: ETS 6: 110 J / 30 VmAh ETS 12.5 - ETS 400: 60 J / 17 VmAh KVS 15 / KVS 42: 60 J / 17 VmAh ETS 12.C - ETS 100C: 55 J / 15 VmAh KVS 2C / KVS 5C: 55 J / 15 VmAh CCMT 2 - CCMT 8: 60 J / 17 VmAh CCMT 16 - CCMT 42: 175 J / 49 VmAh CTTR 20: 60 J / 17 VmAh |
| | RS-485 RTU (only for EKE 1B and 1C) | Galvanic isolation. No Built-in termination. Supported commands with max. of 50 ms response time: 0 x 03, 0 x 04, 0 x 06 Supported commands without defined max response time : 0x08, 0x10, 0x14, 0x15,0x2b |
| Communication | CAN | EKE 1A/1B: CANOpen over RJ12 connector. EKE 1C: CANOpen over CAN 4pin terminal and RJ12 connector. EKE 1D: CANOpen over CAN 3pin terminal and RJ12 connector. NOTE: For EKE EKE 1A/1B, RJ12 connector is used directly connect and supply a user interface MMI Refer to the user guide for information about type of connection cables |

Environmental conditions:

Table 7: Environmental conditions

| Feature | Description | | |
|---|--|--|--|
| Operating conditions | -20 – 60 °C, 90% RH non-condensing | | |
| Storage / Transport conditions | -30 – 80 °C, 90% RH non-condensing | | |
| Vibration and shock | According to IEC 60068-2-27 Ea | | |
| Integration | In Class I and / or II appliances | | |
| Index of protection | IP40 only on the front cover (General IP20) | | |
| PCB protection | None (no conformal coating) | | |
| Period of electric stress across insulating parts | Long | | |
| Resistance to heat and fire | Category D | | |
| | Immunity against voltage surges Category II | | |
| Approvals | CE compliance: This product is designed to comply with the following EU standards: Low voltage guideline: 2014/35/EU Electromagnetic compatibility EMC: 2014/30/EU and with the following norms EN61000-6-1. EN61000-6-3, (immunity and emission standard for residential. commercial and lightin-dustrial environments) EN61000-6-2. EN61000-6-4, (immunity and emission standard for industrial environments) EN60730-1 and EN60730-2-9 (Automatic electrical controls for household and similar use) ROHS compliance to 2011/65/EU and no components from negative list acc. to 500B0751 | | |



Identification

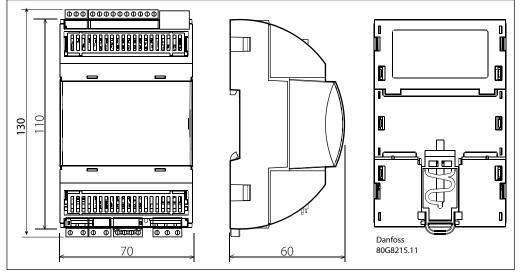
Product label is positioned in the front of the product

Figure 4: Example EKE 1C



Dimensions and weights



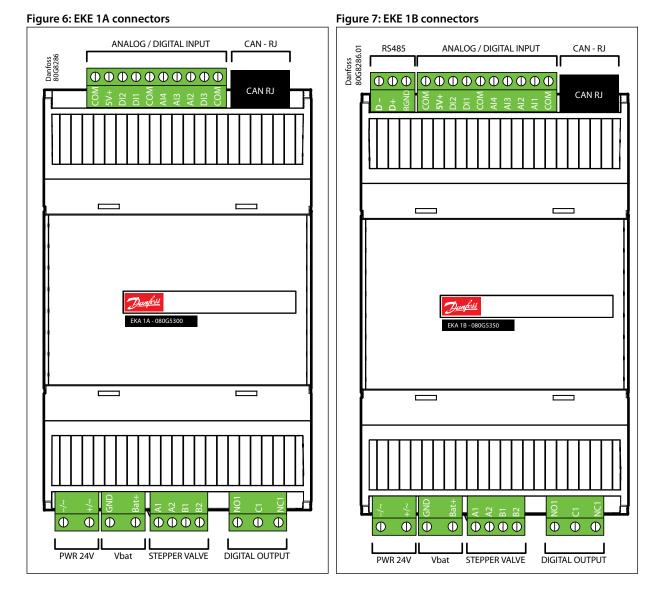


Net Weight:

- EKE 1C: 170 g
- EKE 1A / EKE 1B / EKE 1D: 130 g



Connections:





_

| Danfoss 80G8286.01 | CAN ANALOG / DIGITAL INPUT CAN - RJ |
|-----------------------|---|
| Dan 80G | COM H H H H H H H H H H H H H H H |
| | |
| | |
| | |
| | Superheat controller EKA 1D- 080G5360 |
| | |
| | $\begin{array}{c c} & & & \\ \hline & & -/ \\ \hline & & 0 \\ \hline \hline & 0 \\ \hline & 0 \\ \hline & 0 \\ \hline & 0 \\ \hline \hline & 0 \\ \hline & 0 \\ \hline \hline \hline \hline & 0 \\ \hline \hline \hline \hline \hline \\ \hline \hline \hline \hline \hline \hline \hline \hline \\ \hline \hline$ |
| | PWR 24V Vbat STEPPER VALVE DIGITAL OUTPUT |

Figure 8: EKE 1D connectors



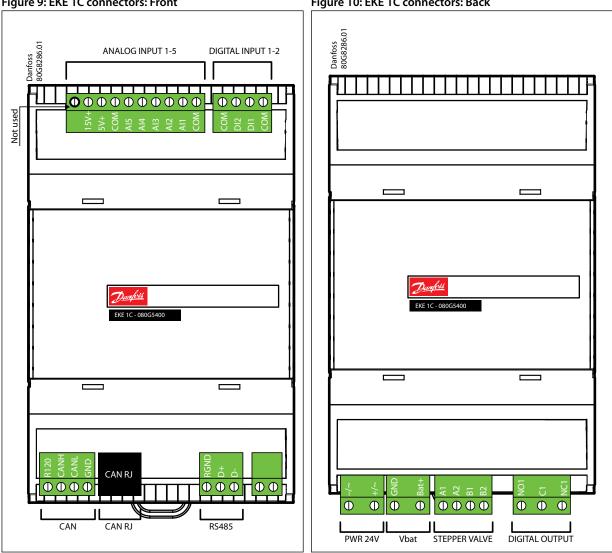


Figure 9: EKE 1C connectors: Front

Figure 10: EKE 1C connectors: Back



Connection diagrams

Figure 11: EKE 1A connection overview

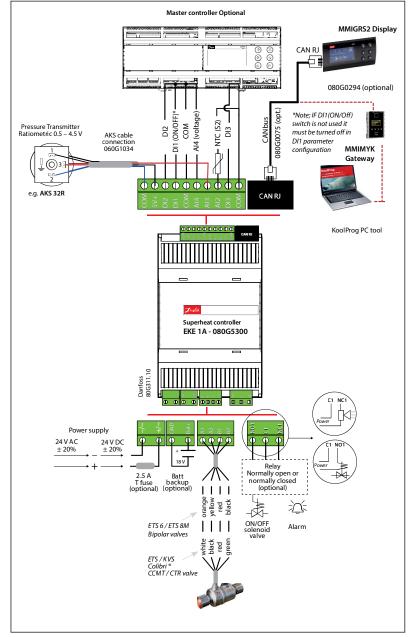


Table 8: EKE 1A pinout

| Table of Life Internout | | |
|-------------------------|--|---------------------------|
| СОМ | Common | |
| DI3 | Digital input 3 | Software configurable DI |
| AI2 | Analog input NTC 10K | S2 |
| Al3 | Analog inputs 0 – 5 V / Ratiometric pressure transmitter | Pe |
| Al4 | analog inputs 0 – 10 V | External Reference signal |
| СОМ | Common | |
| DI1 | Digital input 1 | Main switch (hardware) |
| DI2/3 | Digital input 2 and 3 | Software configurable DI |
| 5V+ | Power output for Ratiometric pressure transmitter 0 – 5V | |
| СОМ | Common | |
| | | |

• NOTE:

If DI1(On/Off) switch is not used it must be short circuited



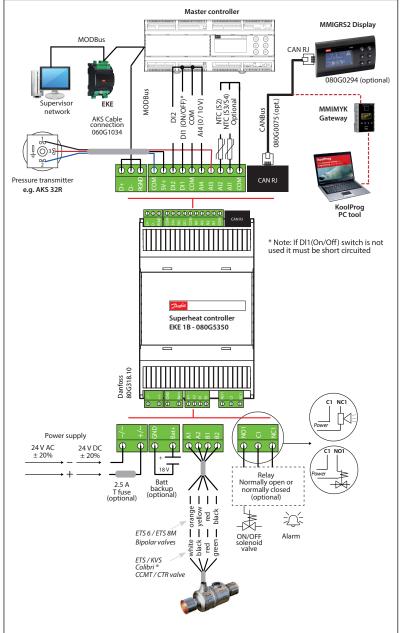


Figure 12: EKE 1B connection overview

Table 9: EKE 1B pinout

| СОМ | Common | |
|-------|--|-------------------------------|
| AI | Analog inputs NTC 10K | S3/S4 selectable via software |
| AI2 | Analog input NTC 10K | S2 |
| A13 | Analog inputs 0 – 5 V / Ratiometric pressure transmitter | Pe |
| Al4 | analog inputs 0 – 10 V | External Reference signal |
| СОМ | Common | |
| DI1 | Digital input 1 | Main switch (hardware) |
| DI2/3 | Digital input 2 and 3 | Software configurable DI |
| 5V+ | Power output for Ratiometric pressure transmitter 0 – 5V | |
| СОМ | Common | |

• NOTE:

If DI1(On/Off) switch is not used it must be short circuited



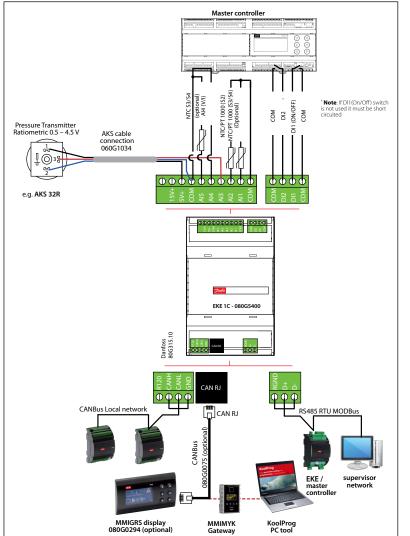


Figure 13: EKE 1C - Front board connection overview

Table 10: EKE 1C pinout

| • | | |
|------|---|-------------------------------|
| сом | Common | |
| Al1 | Analog inputs temperature NTC 10K / PT1000 | S3/S4 selectable via software |
| AI2 | Analog inputs temperature NTC 10K / PT1000 | S2 |
| AI3 | Analog inputs voltage / current | Pe |
| Al4 | Analog inputs voltage / current | Ext. Ref. or Pc |
| AI5 | Analog inputs NTC temperature | S3/S4 selectable via software |
| СОМ | Common | |
| 5V+ | Power outputs for Ratiometeric pressure transmitter 0 $-5V$ | |
| 15V+ | Power output for current signal pressure transmitter | |
| DI1 | Digital input 1 | Main switch (hardware) |
| DI2 | Digital input 2 | Software configurable DI |
| 24V+ | Not used in EKE 1C | |
| A01 | Not used in EKE 1C | |
| | | |

O NOTE:

If DI1(On/Off) switch is not used it must be short circuited



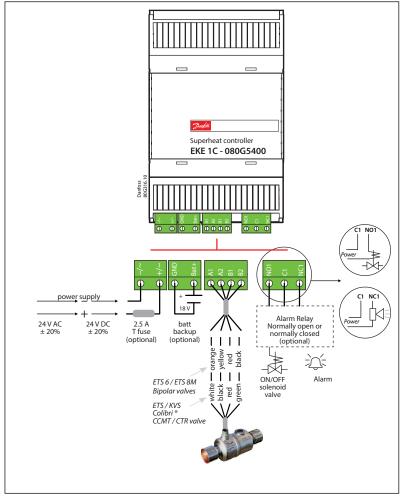


Figure 14: EKE 1C - Back board connection overview

Different types of 4 - 20 mA pressure Transmitters need different supply levels. Check the guide bellow

| Table 11: EKE 1C pressure transmitters range |
|--|
|--|

| Tuble Th ERE Te pressure transmitters range | | | | |
|---|---------------------------------|---------------------|--|--|
| User selection EKE connection | Signal | EKE Connection | | |
| Not defined | - | - | | |
| AKS 32R | Ratiometric 10-90% | 5V supply from EKE | | |
| 112CP (Sensata) | Ratiometric 10-90% | 5V supply from EKE | | |
| OEM Ratio | Defined by parameters | 5V supply from EKE | | |
| NSK (Saginomiya) | Ratiometric 10-90%, 0.5 to 4.5V | 5V supply from EKE | | |
| AKS 32 1-5V | 1-5V | 15V supply from EKE | | |
| OEM Voltage | Defined by parameters | 15V supply from EKE | | |
| Bus shared | Via RS485 Modbus | - | | |
| AKS 32 1-6V | 1-6V | 15V supply from EKE | | |
| AKS 32 0-10V | 0-10v | 15V supply from EKE | | |
| AKS 33 | 4-20mA | 15V supply from EKE | | |
| XSK (Saginomiya) | 4-20mA | 15V supply from EKE | | |
| OEM Current | Defined by parameters | 15V supply from EKE | | |
| | | | | |

O NOTE:

EKE 1A/1B/1D only support ratiometric 0.5 to 4.5V pressure transmitter



Figure 15: Connection for 4 - 20 mA

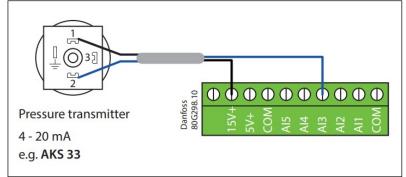


Figure 16: EKE 1D connection overview

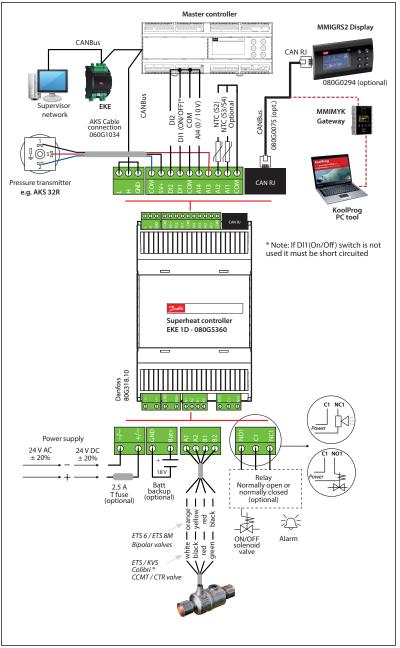




Table 12: EKE 1D pinout

| СОМ | Common | |
|-------|--|-------------------------------|
| AI | Analog inputs NTC 10K | S3/S4 selectable via software |
| AI2 | Analog input NTC 10K | S2 |
| AI3 | Analog inputs 0 – 5 V / Ratiometric pressure transmitter | Pe |
| Al4 | analog inputs 0 – 10 V | External Reference signal |
| СОМ | Common | |
| DI1 | Digital input 1 | Main switch (hardware) |
| DI2/3 | Digital input 2 and 3 | Software configurable DI |
| 5V+ | Power output for Ratiometric pressure transmitter 0 – 5V | |
| СОМ | Common | |

<u>Mounting</u>

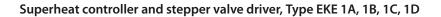
DIN rail mounting / demounting. The unit can be mounted onto a 35 mm DIN rail simply by snapping it into place and securing it with a stopper to prevent sliding. It is demounted by gently pulling the stirrup located in the base of the housing

2(2)

"Click" (3)

Figure 17: Mounting

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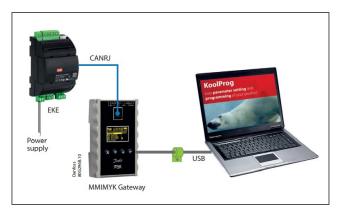
User interface

Koolprog software tool

KoolProg is a software tool that can configure the EKE Controllers in fast and easy way

The main features of the KoolProg are listed as follows

- Make Online changes to parameter configurations
- Monitor live status of inputs and outputs
- Quickly analyze controller behavior. and program patterns by using the graphical trending tool. KoolProg Software is available for download free of charge at http://koolprog.danfoss.com. The customer will first be guided through a registration process before download can commence



O NOTE:

For updated EKE software versions it is required to install the latest KoolProg software versions to have the full compatibility To guarantee a reliable USB connection to a host device (e.g. industrial PC), you must: keep USB cable length < 1 m. Kool Prog software do not support multiple EKE controllers in a daisy chain network. EKE must be powered up before starting programming. The user must make the program for EKE based on the product version and software version. EKE will not be programmed correctly if uploaded program with wrong version



- Create your own configuration files on your PC without having to connect a controller
- Import a parameter configuration file to your PC from a connected controller. Save the file and download it to other controllers of the same model
- Select the most frequently used parameters as your favorites
- Find all the technical documentation for each controller model within one location

Quickly program one. or multiple controllers by using the progress and completion status indicators

- Quickly analyze controller behavior and program
- patterns by using the graphical trending tool Make Online changes to parameter configurations
- Monitor live status of inputs and outputs

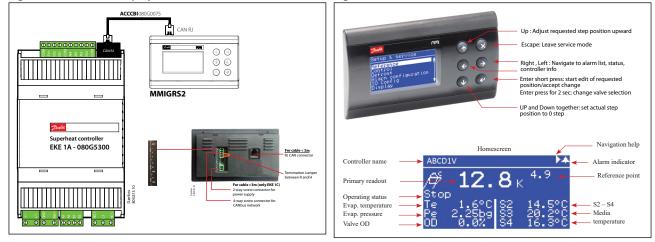
User interface Display MMIGRS2

MMIGRS2 is a remote interface that connects with EKE controller through the CAN RJ or CANbus network. All the information about the user interface is loaded inside the EKE controller; that's why there is no need of programming the MMIGRS2 interface. MMIGRS2 is powered externally or from the controller which it is connected to and automatically shows its user interface.



Figure 19: MMIGRS2 Display connection with EKE

Figure 20: MMIGRS2 Main screen



On the main screen the following data are displayed:

- the main analog inputs measurements or other information
- the icon indicating if unit is operating in superheat mode or temperature mode
- · shows the status of the controller
- the alarm or service icon

O NOTE:

When MMI is not connected to EKE via telephone cable the autodetection feature of the EKE CAN address will not work. Therefore check the following MMIGRS2 setting: 1) enter BIOS menu pressing and holding X + Enter keys for 5 s 2) select "MCXselection"->" Manual Mode" and set the CAN address of the EKE you wish to connect to.

• NOTE:

To use EKE 1x controllers with MMI using RJ 12 cable, The CAN R and H terminals behind MMI should be shorted. If CAN wired connections are used, the first and the last node in the CAN connection should be terminated using 120-ohm resistor

Operation System Master

EKE 1x superheat controller can be interfaced with a System Master the over the network or via analog or digital signals. The master could be e.g., a Danfoss MCX controller or a PLC system

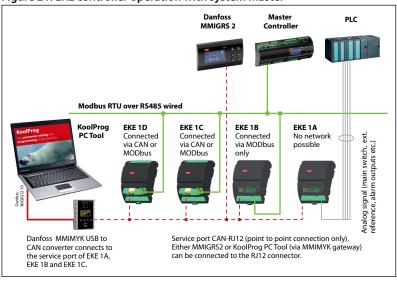


Figure 21: EKE controller operation with system master

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Alarms

Table 13: Alarms

| Label | Alarm name | Modbus PNU | Bit number | Can Index | Can Subindex | Bit number |
|-------|--|------------|------------|-----------|--------------|------------|
| E100 | Valve configuration error | 1901 | 8 | 5507 | 6C | 0 |
| E101 | Configuration error | 1901 | 9 | 5507 | 6C | 1 |
| E102 | Sensor supply over- load | 1901 | 10 | 5507 | 6C | 2 |
| E024 | S2 suction pipe sen- sor error | 1901 | 11 | 5507 | 6C | 3 |
| E025 | S3 media inlet sensor error | 1901 | 12 | 5507 | 6C | 4 |
| E026 | S4 media outlet sen- sor error | 1901 | 13 | 5507 | 6C | 5 |
| E020 | Pe evaporator trans- mitter error | 1901 | 14 | 5507 | 6C | 6 |
| E121 | Pc condenser trans- mitter error | 1901 | 15 | 5507 | 6C | 7 |
| E019 | External reference sig- nal alarm | 1901 | 0 | 5507 | 6C | 8 |
| E011 | No refrigerant selec- ted | 1901 | 1 | 5507 | 6C | 9 |
| E103 | No valve configured | 1901 | 2 | 5507 | 6C | 10 |
| E122 | Shared signal timeout | 1901 | 3 | 5507 | 6C | 11 |
| E128 | Ext. ref. signal timeout | 1901 | 4 | 5507 | 6C | 12 |
| A997 | Battery critical low voltage | 1901 | 5 | 5507 | 6C | 13 |
| A996 | Battery too high volt- age | 1901 | 6 | 5507 | 6C | 14 |
| W001 | Battery low voltage | 1901 | 7 | 5507 | 6C | 15 |
| A994 | Low S4 media outlet temperature | 1902 | 8 | 5507 | 6C | 16 |
| A993 | High temperature | 1902 | 9 | 5507 | 6C | 17 |
| A992 | Low temperature | 1902 | 10 | 5507 | 6C | 18 |
| A991 | High evaporation pressure (MOP) | 1902 | 11 | 5507 | 6C | 19 |
| A990 | Low evaporation pres- sure (LOP) | 1902 | 12 | 5507 | 6C | 20 |
| A989 | High condensing tem- perature | 1902 | 13 | 5507 | 6C | 21 |
| A988 | High superheat | 1902 | 14 | 5507 | 6C | 22 |
| A987 | Low superheat | 1902 | 15 | 5507 | 6C | 23 |
| A986 | Lack of valve capacity | 1902 | 0 | 5507 | 6C | 24 |
| W002 | Standby mode | 1902 | 1 | 5507 | 6C | 25 |
| W003 | Manual control | 1902 | 2 | 5507 | 6C | 26 |
| E104 | SH reference too close to SH close setpoint | 1902 | 3 | 5507 | 6C | 27 |
| E105 | LOP setpoint too close to MOP setpoint | 1902 | 4 | 5507 | 6C | 28 |
| E129 | No sensor configured for S4 | 1902 | 5 | 5507 | 6C | 29 |
| E106 | No sensor configured for S3 | 1902 | 6 | 5507 | 6C | 30 |
| E107 | SH min higher than SH max | 1902 | 7 | 5507 | 6C | 31 |
| E108 | OD min higher than OD max | 1903 | 8 | 5507 | 6E | 0 |
| E109 | No transmitter config- ured for Pc | 1903 | 9 | 5507 | 6E | 1 |
| E114 | Check valve step mode vs positioning | 1903 | 10 | 5507 | 6E | 2 |
| E115 | Valve speed too fast | 1903 | 11 | 5507 | 6E | 3 |
| E116 | Valve speed too slow | 1903 | 12 | 5507 | 6E | 4 |



Superheat controller and stepper valve driver, Type EKE 1A, 1B, 1C, 1D

| Label | Alarm name | Modbus PNU | Bit number | Can Index | Can Subindex | Bit number |
|-------|---|------------|------------|-----------|--------------|------------|
| E117 | Valve emergency speed too fast | 1903 | 13 | 5507 | 6E | 5 |
| E118 | Valve emergency speed too slow | 1903 | 14 | 5507 | 6E | 6 |
| E119 | Valve start speed too slow | 1903 | 15 | 5507 | 6E | 7 |
| A999 | DI1 unstable input | 1903 | 0 | 5507 | 6E | 8 |
| A998 | DI2 unstable input | 1903 | 1 | 5507 | 6E | 9 |
| A983 | DI3 unstable input | 1903 | 2 | 5507 | 6E | 10 |
| E125 | AI5 cant operate with AKS sensor | 1903 | 4 | 5507 | 6E | 12 |
| E126 | Valve short circuit or driver too hot | 1903 | 5 | 5507 | 6E | 13 |
| A982 | Thermostatic signal missing | 1903 | 6 | 5507 | 6E | 14 |
| A981 | SH control signal missing | 1903 | 7 | 5507 | 6E | 15 |
| E123 | Low supply voltage | 1904 | 8 | 5507 | 6E | 16 |
| E132 | No sensor configured for S2 | 1904 | 9 | 5507 | 6E | 17 |
| E133 | No transmitter config- ured for Pe | 1904 | 10 | 5507 | 6E | 18 |
| E134 | Ext. ref configuration error | 1904 | 11 | 5507 | 6E | 19 |
| E135 | DI H/C cant operate with the thermostat | 1904 | 12 | 5507 | 6E | 20 |
| A984 | PWR Backup module failure | 1904 | 13 | 5507 | 6E | 21 |
| A985 | Replace PWR Backup module | 1904 | 14 | 5507 | 6E | 22 |



Ordering

Table 14: Product part numbers

| Description | Pack format | CodeNo. |
|------------------------------|-------------|----------|
| Electronic controller EKE 1A | Single pack | 080G5300 |
| Electronic controller EKE 1B | Single pack | 080G5350 |
| Electronic controller EKE 1C | Single pack | 080G5400 |
| Electronic controller EKE 1D | Single pack | 080G5360 |

Table 15: Accessories part numbers

| Description | Pack format | CodeNo. |
|---|-------------|----------|
| MMIGRS2 Remote Display | Single pack | 080G0294 |
| MMIMYK gateway | Single pack | 080G0073 |
| ACCCBI telephone cable user interface connector 1.5 m | Single pack | 080G0075 |
| Backup power module, EKE 2U | Single pack | 080G5555 |
| Power supply, AK-PS 063 STEP3 | Single pack | 080Z0057 |
| Power supply, AK-PS 130 STEP3 | Single pack | 080Z0058 |
| Power supply, AK-PS 250 STEP3 | Single pack | 080Z0059 |



Certificates, declarations, and approvals

The list contains all certificates, declarations, and approvals for this product type. Individual code number may have some or all of these approvals, and certain local approvals may not appear on the list.

Some approvals may change over time. You can check the most current status at danfoss.com or contact your local Danfoss representative if you have any questions.

File name Document type Document topic Approval authority 080R4003.01 EU Declaration of conformity EMC directive 2014/30/EU: EN61000-6-3: 2007 +A1: 2011 EN61000-6-2: 2005 Danfoss UVD directive 2014/35/EU: EN60730-1: 2011 EN60730-2-9: 2010 RoHS directive 2011/65/EU Danfoss

Table 17: Approvals



Online support

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